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FINAL REPORT

DESIGN OF MOBILE TRACKING SYSTEM

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Abstract

This report presents the whole construction of the Design Of A Mobile Tracking Robot. Result will be taken to make sure that the device is working smoothly in the whole operation.

The main idea of the Mobile Tracking Robot is to save human power while they are trying to carry something in a smatter way. This device will automatically follow the signal transmitted by a transmitter held by the owner. The device will follow the owner wherever the owner heading for. It would be a good device for those who prefer for a good helper for carrying things.

In order the device is applicable for any environment, many research should be made in the tracking part. Sensors play a very important role in this project. During the tracking system is taking part, it should be flexible enough to avoid obstacle around it when is it near the device.